

IN THE CLAIM:

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1. (Original) A process for recognizing the movement of a motor vehicle comprising the steps:

measuring the accelerating forces acting on the motor vehicle at preset time intervals by a acceleration sensor as time-dependent functions and sending the functions to an evaluating and control unit;

determining a frequency spectrum of the functions with the evaluating and control unit on the basis of a Fourier analysis;

if a preset percentage of the frequency spectrum is below a set limit frequency, storing, with the evaluating and control unit, information indicating that the motor vehicle was moved; and

if the preset percentage of the frequency spectrum is not below the set limit frequency, storing, with the evaluating and control unit, information indicating that the motor vehicle was not moved.

2. (Original) A process in accordance with claim 1, wherein the accelerating forces acting on the motor vehicle are measured by the acceleration sensor in at least two mutually independent directions.

3. (Original) A process in accordance with claim 1, wherein the frequency spectrum is determined on the basis of a discrete Fourier analysis.